

WHAT IS CLAIMED IS:

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1. A system comprising:  
a general purpose DMA controller;  
an arithmetic circuit, the arithmetic circuit being coupled to receive  
5 data from the general purpose DMA controller, the arithmetic circuit  
generating an error checking value based on the data received from the  
general purpose DMA controller and based on a polynomial equation.

10 2. A system according to claim 1, wherein the arithmetic circuit is  
capable of being programmed with a plurality of different polynomial equations  
usable to generate error checking values of different types.

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15 3. A system according to claim 2, wherein the arithmetic circuit is a  
linear feedback shift register wherein the linear feedback shift register includes a  
plurality of feedback points, the feedback points determining the form of a  
polynomial that is used in the polynomial equation, and wherein the feedback points  
are programmable.

20 4. A system according to claim 3, wherein the linear feedback shift  
register comprises a plurality of the multiplexers, and wherein each multiplexer is  
programmable to determine whether a polynomial in the polynomial equation has a  
particular exponential term.

25 5. A system according to claim 4, wherein the system further comprises  
a programmable shift register, the programmable shift register being programmable  
to shift different block sizes of data into the linear feedback shift register.

6. A system according to claim 5, wherein the linear feedback shift  
register is capable of being programmed with divisor polynomials having each of the  
25 following forms:  $x^{16} + x^{15} + x^2 + 1$ ;  $x^{16} + x^{14} + x + 1$ ;  $x^{16} + x^{12} + x^5 + 1$ ;  $x^{16} +$   
 $x^{11} + x^4 + 1$ ; and  $x^{32} + x^{26} + x^{23} + x^{22} + x^{16} + x^{12} + x^{11} + x^{10} + x^8 + x^7 + x^5 +$   
 $x^4 + x^2 + x + 1$ .

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7. A system according to claim 1, wherein the arithmetic circuit performs polynomial division, and wherein the divisor polynomial is programmable.

8. A system according to claim 1, wherein the error checking value is a cyclic redundancy check value.

5 9. A system according to claim 1, wherein the polynomial equation includes a polynomial with a plurality of exponential terms, and wherein the system further comprises a polynomial register comprising a plurality of bits, each bit determining whether a particular exponential term is present in the polynomial of the polynomial equation.

10 10. A system according to claim 1, wherein the general purpose DMA controller is capable of controlling DMA communication of data from a universal asynchronous transmitter-receiver, a memory controller, and a serial port interface.

11. A system comprising:

(A) a general purpose DMA controller;

15 (B) a linear feedback shift register, the linear feedback shift register being coupled to receive data from the general purpose DMA controller, the linear feedback shift register comprising a plurality of programmable polynomial building blocks, the plurality of programmable polynomial building blocks being connected in a sequence with each building block corresponding to a respective exponential term in a polynomial of a polynomial equation implemented by the linear feedback shift register, each building block comprising

20 (1) a feedback gate, the feedback gate being coupled to an output of an adjacent polynomial building block in the sequence and to a non-adjacent polynomial building block in the sequence,

25 (2) a multiplexer, the multiplexer being coupled to an output of the feedback gate and to the output of the

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adjacent polynomial building block in the sequence, the multiplexer determining whether the flip flop receives an input from an output of the feedback gate or from the output of the adjacent polynomial building block,

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- (3) a flip flop, the flip flop having an input coupled to an output of the multiplexer, and

wherein, when the flip flop receives an input from the output of the feedback gate, the respective exponential term is included in the polynomial;

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wherein, when the flip flop receives an input from the immediately-preceding flip flop, the respective exponential term is not included in the polynomial; and

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wherein the multiplexers of each of the programmable polynomial building blocks are programmable to determine which of the exponential terms are included in the polynomial of the polynomial equation.

12. A system according to claim 11, wherein the linear feedback shift register performs polynomial division, and wherein the polynomial is a polynomial divisor.

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13. A system according to claim 11, wherein the system further comprises a polynomial register comprising a plurality of bits, each bit determining whether a particular exponential term is present in the polynomial of the polynomial equation.

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14. A system according to claim 11, wherein the system further comprises a programmable shift register, the programmable shift register being programmable to shift different block sizes of data into the linear feedback shift register.

15. A system according to claim 11, wherein the general purpose DMA controller is capable of controlling DMA communication of data from a universal asynchronous transmitter-receiver, a memory controller, and a serial port interface.

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16. A circuit according to claim 11, wherein the feedback gate is an XOR gate.

5 17. A system according to claim 11, wherein the linear feedback shift register is capable of being programmed with a divisor polynomial having the following form:  $x^{16} + x^{15} + x^2 + 1$ .

18. A system according to claim 11, wherein the linear feedback shift register is capable of being programmed with a divisor polynomial having the following form:  $x^{16} + x^{12} + x^5 + 1$ .

10 19. A system according to claim 11, wherein the linear feedback shift register is capable of being programmed with a divisor polynomial having the following form:  $x^{16} + x^{11} + x^4 + 1$ .

15 20. A system according to claim 11, wherein the linear feedback shift register is capable of being programmed with a divisor polynomial having the following form:  $x^{32} + x^{26} + x^{23} + x^{22} + x^{16} + x^{12} + x^{11} + x^{10} + x^8 + x^7 + x^5 + x^4 + x^2 + x + 1$ .

20 21. A system according to claim 11, wherein the linear feedback shift register is capable of being programmed with divisor polynomials having each of the following forms:  $x^{16} + x^{15} + x^2 + 1$ ;  $x^{16} + x^{14} + x + 1$ ;  $x^{16} + x^{12} + x^5 + 1$ ;  $x^{16} + x^{11} + x^4 + 1$ ; and  $x^{32} + x^{26} + x^{23} + x^{22} + x^{16} + x^{12} + x^{11} + x^{10} + x^8 + x^7 + x^5 + x^4 + x^2 + x + 1$ .

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